

mission

during EVA

Figure 1. Methodological workflow of the analysis approach from the various data sources in the field to the research questions and prediction models. The arrow on the left indicates a chronology of the different steps in the approach. The 3D-environmental-model under *Data Integration* shows alternative traverse paths (a, b, c) to a specific point of interest (POI). The model is derived from aerial drone imaging and rover's LiDAR imaging for high surface resolution. *Analysis & Prediction* shows preliminary results of the proof-of-concept study. The graphs show the individual pre- and post-data of an analog astronaut over an averaged gait cycle. The red-shaded area marks the fatigue-induced alterations in the gait parameters.